

# SOLEIL and SYMETRIE company collaboration to build Tango ready in-vacuum diffractometer



Y.M. Abiven\*, N. Aubert, G. Ciatto, C. Engblom, P. Fontaine, S. Zhang,  
(Synchrotron Soleil, Paris, France), A. L'Hostis<sup>†</sup>, P. Noire, O. Dupuy,  
T. Roux (SYMETRIE, Nîmes, France)

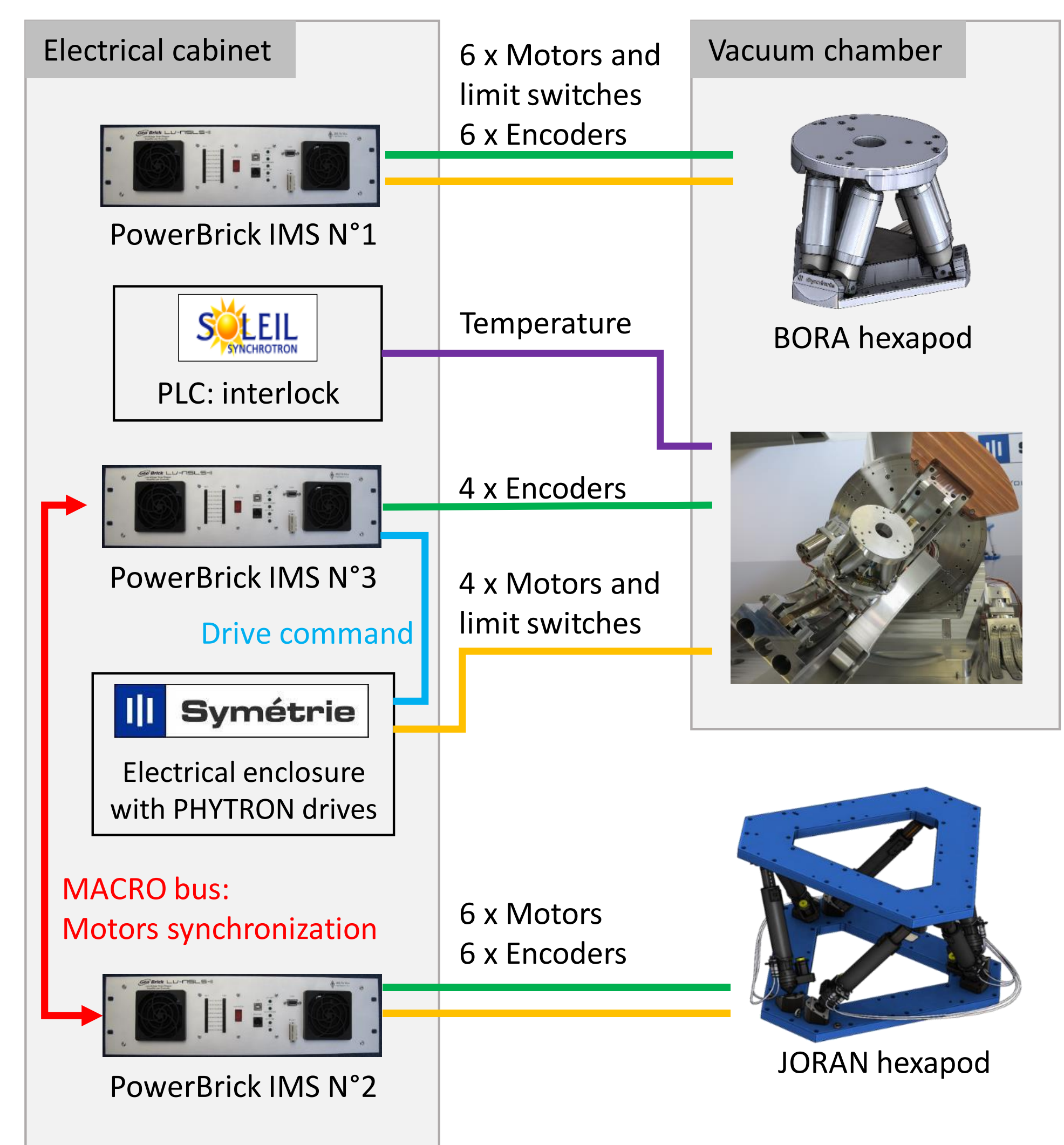
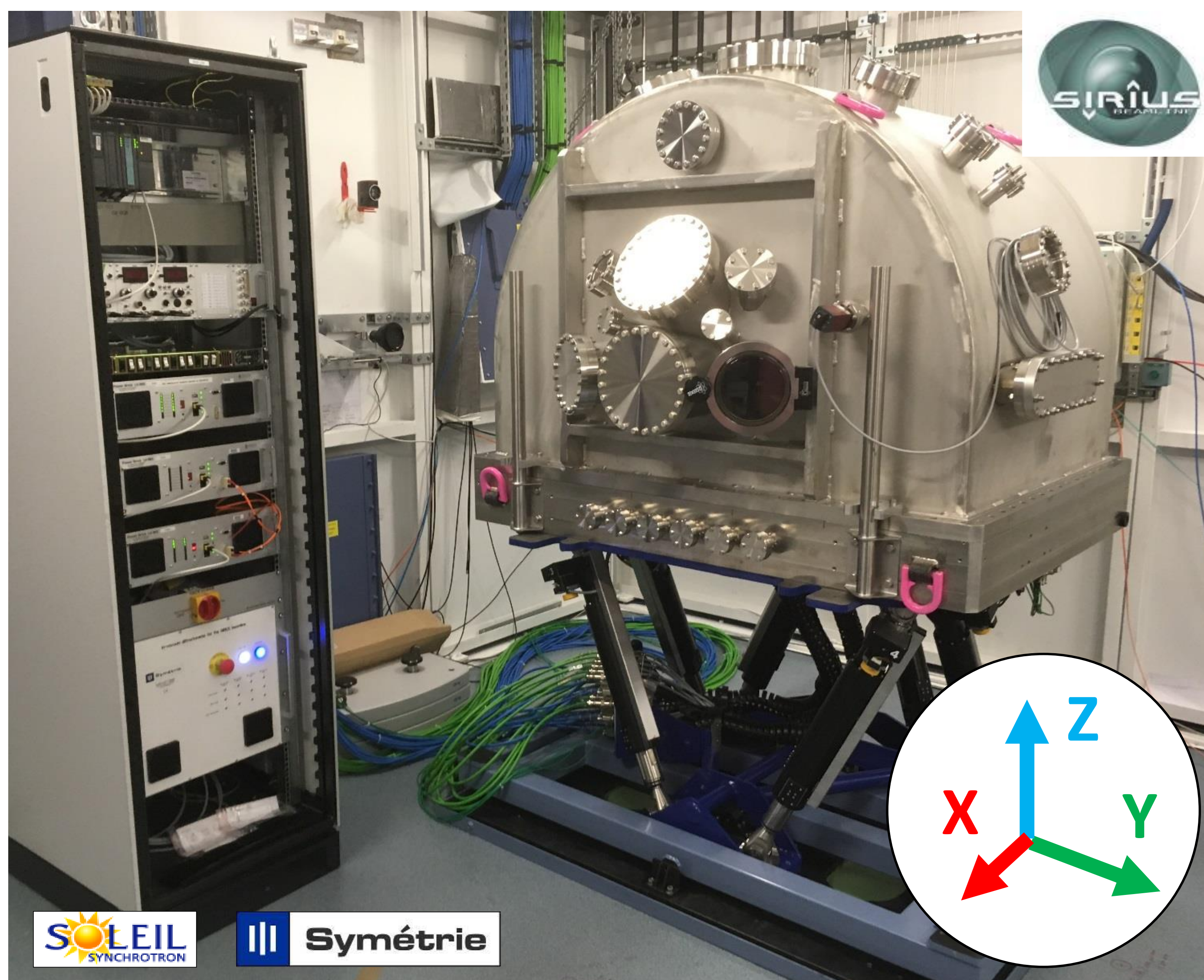


\* yves-marie.abiven@synchrotron-soleil.fr

**Context :** SOLEIL (France) and MAXIV (Sweden) Joint project developed by SYMETRIE company and complementarily funded by an Ile-de-France region project (DIM OxyMORE) [1]

**SIRIUS beamline diffractometer** composed of 3 subsystems:

- **JORAN hexapod** at the bottom (carries the system with the vacuum vessel), and **used to align the center of the diffractometer.**
- **4-circle in-vacuum diffractometer**
- **BORA hexapod** embedded **inside the diffractometer** and **used to align the sample stage**



Hardware architecture for control

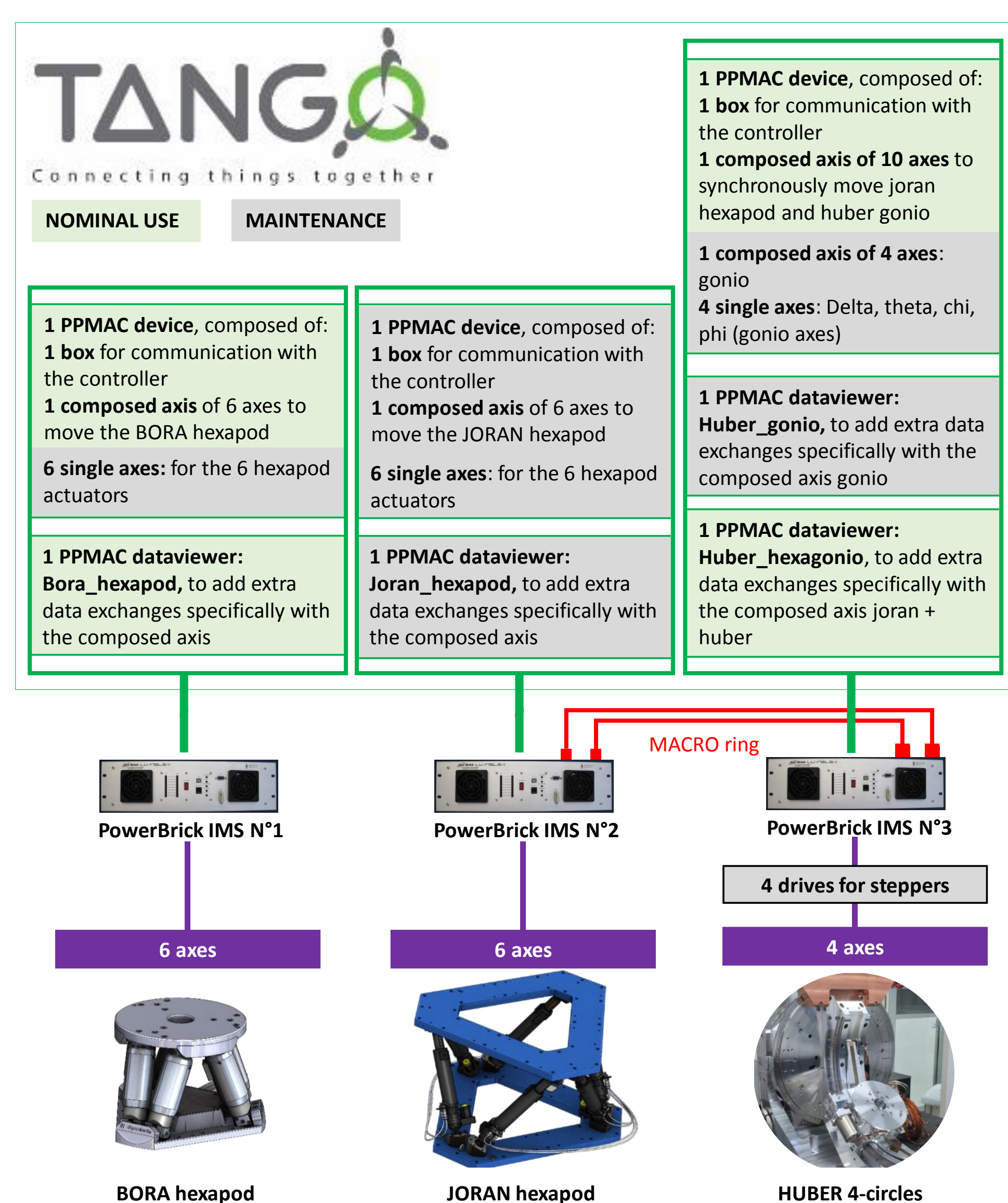
**Control architecture :** Based on Standard SOLEIL hardware and software architecture fully integrated in TANGO.

Hardware devices use **PowerBrick Delta Tau controller** selected in the context of REVOLUTION project at SOLEIL.

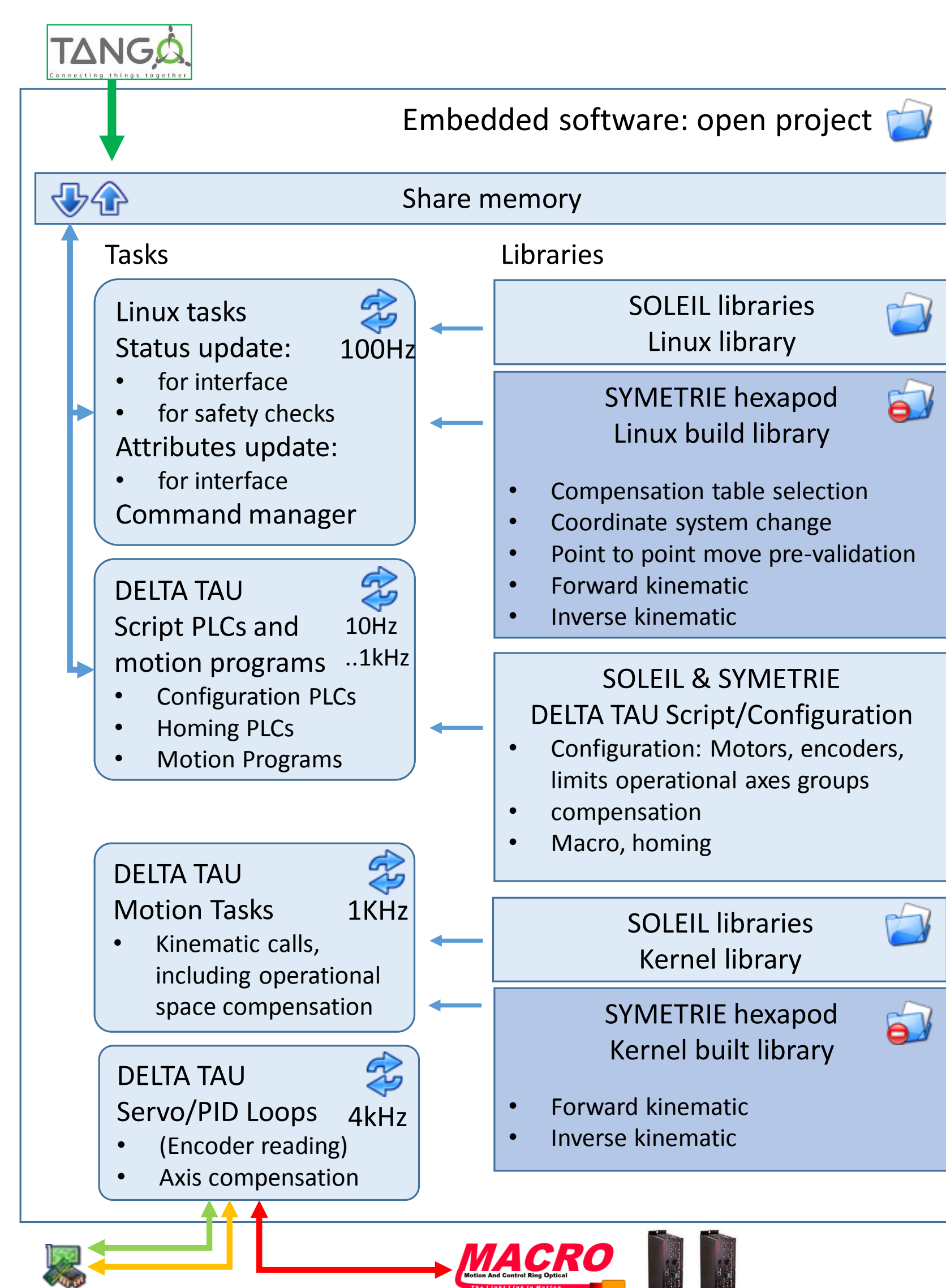
**TANGO Software interface using :**

- Device **PowerPMACBox** for the controller and general data.
- Device **PowerPMACAxis** for driving physical axes.
- Device **PowerPMACComposedAxis** for driving composed virtual axes (one device/CS).
- Device **RawDataViewer**, a diagnostic tool providing read-only raw firmware data of Power PMAC for specified axis.

**Embedded software** manage the **kinematics**, the **hexapod moves pre-validation**, the **coordinate systems changes**, some **real-time security verification**



Tango device and embedded software integration



## Successful Collaboration

**Diffractometer factory acceptance tests :**

- **mechanical integration on the beamline**
- **metrology constraints,**
- **vacuum quality of the chamber,**
- **project management and collaboration successfully achieved**

This project convinced in SOLEIL in the **choice of the DELTA TAU controller** for its systems requiring complex control. It also confirms that the **software architecture is flexible** and well **adapted for collaboration**