



Motion hexapods catalog



Welcome

Welcome to SYMETRIE! In browsing this catalogue, you will find the best possible dynamic solutions to cater to your demanding applications.

Always looking to increase the performance of our hexapods, our growing team works hand in hand to integrate the latest available technology.

This is why SYMETRIE is first and foremost a R&D company. Thanks to our experience providing hexapods for industry and research laboratories, we will be able to quickly answer your needs.

Olivier Lapierre & Thierry Roux Co-founders, CEO & CTO

SYMETRIE company



SYMETRIE's engineering office consists of mechanical, electronic and software engineers. Our R&D department is continuously seeking for improvement, with a major effort on control software.

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In our ISO 7 (class 10000) clean room, we mount the hexapods for applications which are sensible to environmental contamination, such as optics, space or particle accelerators. In a clean room the concentration of particles is controlled and minimized.







All our hexapods and controllers are assembled in our mechanical and electronic workshops using standardized procedures.



To demonstrate high precision performances, SYMETRIE is equipped with a wide range of metrology tools: laser interferometers, laser trackers, coordinate measuring machine (CMM), electronic inclinometers, capacitive sensors.

A promising experience and vision

SYMETRIE's trusted R&D skills led to the birth of the positioning and motion hexapods

SYMETRIE was created in 2001 with the hexapod technology as a baseline. This innovative system was quickly spotted by the highest research institutions which asked SYMETRIE for a high precision hexapod to position the target of the MegaJoule Laser, a high energy inertial confinement fusion device in France.

The following contracts, still more ambitious, trusted the company to add dynamic motion capabilities to its hexapods systems. SYMETRIE succeeded once again in delivering up to 1g acceleration to slosh 10 ton liquid gas tanks for maritime transportation.

The acquired experience and trust built among a nascent network of customers were the beginning of an involvement in a wide array of technological projects, such as the Gaia satellite and the James Webb Space Telescope among others.

Innovation is a key factor of our development. Our R&D department works every day to improve our technologies and control systems using the latest generation components and techniques for higher quality products.

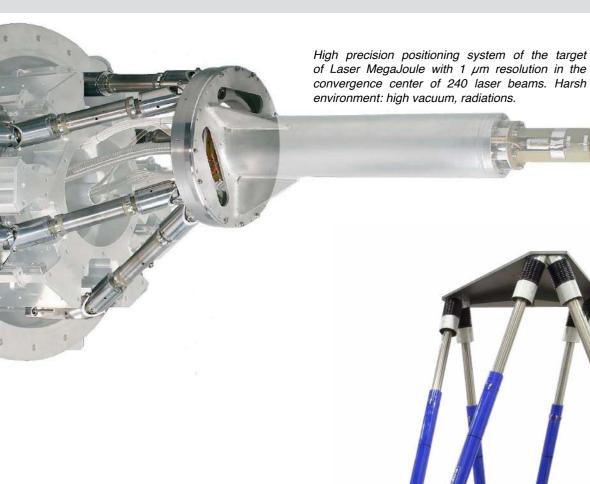
From standard hexapods to custom designs

To cater to your needs in the smoothest way, SYMETRIE offers a range of turnkey hexapods.

- Better price and lead time: We look forward to offering hexapods which have already been designed.
- unique features allows you to easier select and understand the capabilities that you will get.

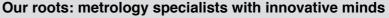
SYMETRIE remains a trustworthy designer for customized solutions and can provide custom designs in a short time thanks to an in-house software enabling to quickly create a hexapod geometry with respect to the customer's input parameters.

With more than 10 years hexapod background, SYMETRIE is experienced in choosing and using the most adapted technologies in terms of motors, encoders, joints... according to the customer's application.



A 4 meter tall swell simulation hexapod with up to 10 ton payload, 1 m/s speed and 1 g acceleration.





MISTRAI

NOTUS

The two co-founders of SYMETRIE, Olivier Lapierre and Thierry Roux, were previously working for LNE, the French national metrology and testing laboratory. Specialized in **dimensional metrology**, they were looking for an innovative and efficient 6 DOF measurement system to quickly calibrate machine-tools and thought of the hexapod as a perfect solution.

The dimensional metrology grain remains running through the veins of SYMETRIE at each one of its footsteps. Thanks to an experienced metrology staff, SYMETRIE knows how to qualify and test the hexapods before delivery to validate conformity.



Ease project definition: Offering a coherent range where the hexapods differentiate between each other with



SIROCCO

AQUILON

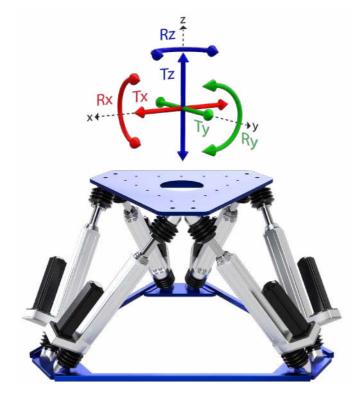
Overview of the product range

6 Degrees Of Freedom

A hexapod is a parallel kinematic structure composed of a mobile platform linked to a fixed platform with 6 actuators.

This design allows to move an object placed on the mobile platform with 6 DOF (Degrees Of Freedom). In other words, the hexapod can move an object along the 3 translations (Tx, Ty, Tz) and the 3 rotations (Rx, Ry, Rz); any combination is possible.







Configurable pivot point

In order to orientate the mobile platform in the desired way, a 3D rotation center has to be defined. This point is not limited to the center of the mobile platform and can be placed wherever the user needs it to be. Pivot point 1 Pivot point 2





ge	Angular travel range	Speed	Height at midrange
m	± 20°	800 mm/s	1.10 m
m	± 20°	1 200 mm/s	1.10 m
m	± 30°	1 000 mm/s	1.44 m
m	± 30°	1 200 mm/s	1.44 m
m	± 30°	1 000 mm/s	1.77 m
m	± 30°	1 200 mm/s	1.77 m
m	± 40°	2 500 m/s	2.85 m
m	± 40°	1 800 m/s	3.31 m

Some applications

Some applications



Motor bench

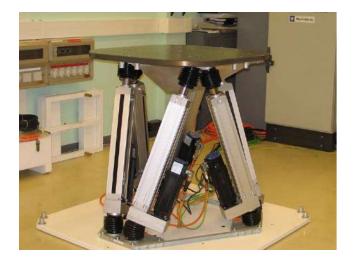
This engine test bench allows to realize de-oiling and dewetting tests by simulating the inclination of the vehicle.

A major French car manufacturers trusted our hexapods to simulate a vehicle movement, in order to reproduce real conditions in factory.

The hexapod can support up to 500 kg equipment load with angles of $+/-51^{\circ}$ in roll and pitch.

After equipping the bench, the user launches a series of automatic tests in order to acquire the various engine parameters (temperature, pressure, etc.) according to the different degrees of freedom.





Motion sensor testing

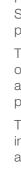
This hexapod has been designed for the control and gualification of high precision inertial motion units.

For this IMU manufacturer, we have integrated a mesuring octopod to the hexapod.

This specific assembly allows the qualification and control of the inertial units during various experiments.

This hexapod is adapted to carry out tests embedded in vehicles. Moreover, a servo-control can be carried out thanks to the information coming from the IMU.







Boat simulation

Here, NOTUS hexapod is simulating a boat deck agitated by the swell, on which a helicopter is trying to land.

This system is installed inside a wind tunnel at a research centre in Canada.

Thanks to this hexapod they recreate outdoor conditions in an indoor test centre, allowing more specific tests to be carried out while limiting costs.





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Wave basin

A wave basin is a research facility for testing ships and offshore structures in the most realistic conditions.

Hexapods are used by maritime laboratories that study the hydrodynamic effects of swell, the phenomena of sloshing or cavitation for example. Wave basins are used by a diversity of naval actors, such as ships and propellers designers, renewable marine energies (floating wind turbines) and offshore (floating production units, anchored or articulated).

The hexapod is attached downwards to a trolley, which moves along the basin. The mobile platform of the hexapod moves the ship model or any other tested component to reproduce the hydrodynamics effects of the swell.

The hexapod is prepared for the maritime environment and the fixed platform is reinforced for upside down use.

Antenna testing

Hexapods are used by the R&D departments developing SATCOM antennas in order to test the stabilization performances of the antennas motorized systems.

These antennas are later installed on boats, trucks or any other kind of vehicles, so the motorization needs to be adjusted in order to enable the highest communication performances between the antenna and the satellite.

These hexapods can be prepared for outdoor and sometimes integrate an extra Rz rotation in the mobile platform to be able to simulate the U-turn of a boat for example.

Sloshing

GazTransport & Technigaz designs containment systems for the transport of LNG (Liquefied Natural Gas). The temperature of LNG is -163°C during transportation so the tanks have to be well isolated to limit LNG evaporation.

GTT is using several dynamic hexapods from SYMETRIE to simulate the impact of sea voyages on their cryogenic membranes. The effects of sloshing, which is the movement of a liquid inside a moving tank, need to be studied by GTT in order to correctly define the width of the membranes and to reinforce them intelligently.

Hexapods have allowed GTT to make great progress in understanding the phenomenon of liquid movements.





Dynamic compact hexapod

KEY FEATURES

- Payload capacity 200 kg
- Linear travel range ± 250 mm
- Angular travel range ± 25°
- Compact



Optics

APPLICATIONS

- Motion simulator
- Naval

- Swell simulator
- Biomedical

NOTUS enables testing the gyroscopic platform of a cold atom gravimeter that will be later installed on a ship by ONERA. The hexapod reproduces the swell motions and the ship vibrations.



NOTUS hexapod allows to test the stabilization system of a camera that can be later installed on a tank, a truck or a boat.

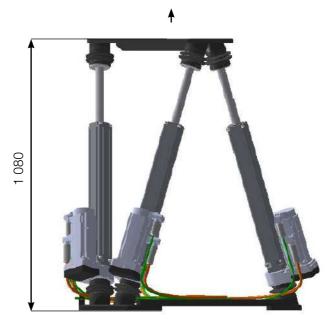


Credits: SPHEREA Test & Services

NOTUS hexapod helps to characterize and calibrate electro-optics gimbals that will be later installed on helicopters.

	NOTUS P	NOTUS V
	for 200 kg payload	for 100 kg payload
Motion and positioning		
Travel range Tx, Ty (mm)	± 250	± 250
Travel range Tz (mm)	± 200	± 200
Travel range Rx, Ry (deg)	± 25	± 25
Travel range Rz (deg)	± 30	± 30
Speed Tx, Ty, (mm/s)	± 800	± 1 200
Speed Tz (mm/s)	± 300	± 600
Speed Rx, Ry, Rz (°/s)	± 50	± 100
Acceleration Tx, Ty (mm/s ²)	10 000	10 000
Acceleration Tz (mm/s ²)	6 000	10 000
Acceleration Rx, Ry, Rz (°/s²)	500	1 000
Mechanical properties		
Payload capacity (kg) (vertical orientation only)	200	100
Motor type	Brushless	Brushless
Miscellaneous		
Operating temperature range (°C)	0 to + 50	0 to + 50
Size mobile platform (mm)	Ø 660	Ø 660
Height in middle position (mm)	~1 080	~1 080
Mass (kg)	~ 120	~ 120
Cable length (m)	7	7
Options	IP 64 motor protection Acquisition and storage of motions API Customized platform design	
Controller		
Interface	Ethernet	
Power supply	400 VAC (three-phase) / 16 A / 50-60 Hz	

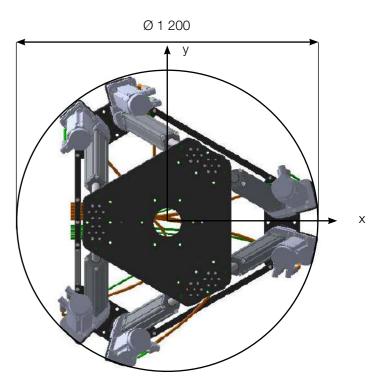
The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.



Ζ

Hexapod in middle position









KEY FEATURES

- Payload capacity up to 1 ton
- Linear travel range ± 460 mm
- Angular travel range ± 30°



Driving simulator

APPLICATIONS

- Motion simulator
- Swell simulator



High payload positioner

MISTRAL hexapod reproduces ship motions to test maritime SATCOM antennas. of large



reactions in a gas deacidification column. These tests allow to improve performance casual surfer or as a performance and and robustness of the processing units. training tool for the professional surfer.



MISTRAL hexapod orientates ship model in a wave basin to reproduce maritime conditions and the shipbuilding techniques. test



The surfer can practice various wave situations played by the Simusurf hexapod and improve his gestures through practice and analysis by recording his movements with additional sensors. Simusurf Hexapod can be used as a discovery and learning tool for the

	MISTRAL 600		MISTRAL 800	
	for 1 000 kg payload (P)	for 500 kg payload (V)	for 1 000 kg payload (P)	for 500 kg payload (V)
Motion and positioning				
Travel range Tx, Ty (mm)	± 400	± 400	± 460	± 460
Travel range Tz (mm)	± 300	± 300	± 400	± 400
Travel range Rx, Ry (deg)	± 30	± 30	± 30	± 30
Travel range Rz (deg)	± 40	± 40	± 40	± 40
Speed Tx, Ty, (mm/s)	1 000	1 200	1 000	1 200
Speed Tz (mm/s)	600	1 000	600	1 000
Speed Rx, Ry (°/s)	50	100	50	100
Speed Rz (°/s)	70	140	70	140
Acceleration Tx, Ty, (mm/s ²)	5 000	8 000	5 000	8 000
Acceleration Tz (mm/s²)	6 000	8 000	6 000	8 000
Acceleration Rx, Ry (°/s²)	500	800	500	800
Acceleration Rz (°/s²)	700	1 100	700	1 100
Mechanical properties				
Payload capacity (kg) (vertical orientation only)	1 000	500	1 000	500
Motor type	Brushless	Brushless	Brushless	Brushless
Miscellaneous				
Operating temperature range (°C)	0 to + 50		0 to + 50	
Size mobile platform (mm)	Ø 1 386		Ø 1 386	
Height in middle position (mm)	~1 440		~1 765	
Mass (kg)	~ 400		~ 450	
Cable length (m)	10		10	
Options	IP 64 motor protection Acquisition and storage of motions API Customized platform desig			
Controller				
Interface	Ethernet			
Power supply	400 VAC (three-phase) / 16 A / 50-60 Hz		

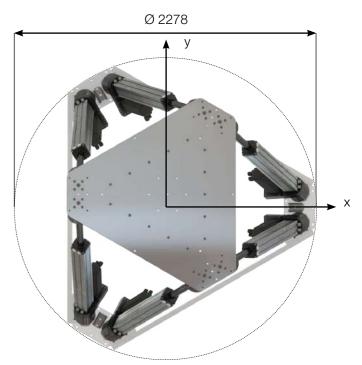
The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.



Hexapod in middle position









Dynamic hexapod with high amplitude

KEY FEATURES

- Payload capacity 2 tons
- Linear travel range ± 600 mm
- Angular travel range $\pm 40^{\circ}$



APPLICATIONS

- Motion simulator
- Swell simulator

- High payloads positioner
- Vehicle simulator



GTT designs cryogenic membrane containment systems used in the shipbuilding industry for the transport of liquid natural gas (LNG). SIROCCO hexapod allows GTT laboratories to study the impact of moving liquid, also called sloshing, on their insulation.



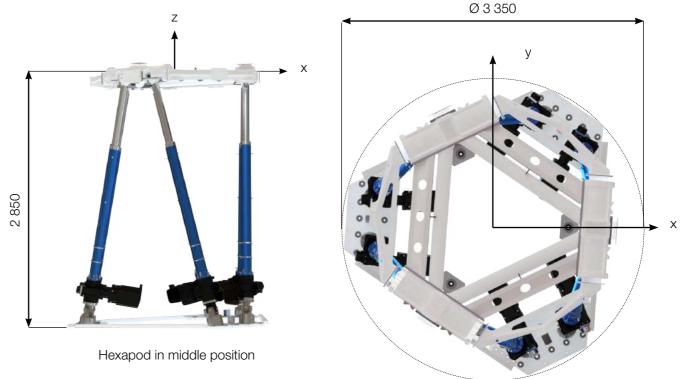
DCNS uses SIROCCO hexapods as submarine simulators for training purposes to reproduce the emergency situations that submarine crews might encounter during a mission.



FMC Technologies uses two SIROCCO XL hexapods to test a ¼ scale LNG loading arm. These hexapods simulate the swell motion to qualify the loading arm that will connect a gas carrier to an offshore gas production factory. One hexapod simulates the gas carrier, the other the offshore factory.

	SIROCCO
Motion and positioning	
Travel range Tx, Ty (mm)	± 600
Travel range Tz (mm)	± 500
Travel range Rx, Ry, Rz (deg)	± 40
Speed Tx, Ty, (mm/s)	± 2 000
Speed Tz (mm/s)	± 1 800
Speed Rx, Ry (°/s)	± 200
Speed Rz (°/s)	± 100
Acceleration Tx, Ty, Tz (mm/s ²)	± 6 000
Acceleration Rx, Ry, (°/s2)	1 200
Acceleration Rz (°/s²)	600
Mechanical properties	
Payload capacity (kg) (vertical orientation only)	2 000
Motor type	Brushless
Miscellaneous	
Operating temperature range (°C)	0 to + 50
Size mobile platform (mm)	Ø 3 350
Height in middle position (mm)	~ 2 850
Mass (kg)	~ 850
Cable length (m)	15
Options	IP 64 motor protection Acquisition and storage of mor API Customized platform design
Controller	
Interface	Ethernet
Power supply	380 VAC (three-phase) / 250 A

The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.











Dynamic hexapod with very high amplitude

KEY FEATURES

- Payload capacity 6 tons
- Linear travel range ± 800 mm
- Angular travel range $\pm 40^{\circ}$



APPLICATIONS

- Motion simulator
- Heavy payload positioner
- Swell simulator



Hexapod AQUILON



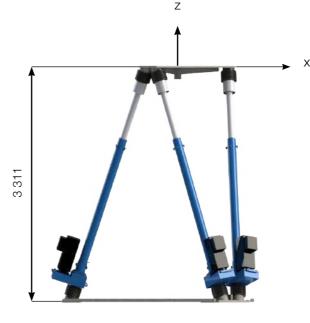


Sloshing tests hexapod AQUILON with a 10T payload tests

	AQUILON
Motion and positioning	
Travel range Tx, Ty (mm)	± 800
Travel range Tz (mm)	± 650
Travel range Rx, Ry, Rz (deg)	± 40
Speed Tx, Ty, (mm/s)	± 1 800
Speed Tz (mm/s)	± 1 600
Speed Rx, Ry (°/s)	± 200
Speed Rz (°/s)	± 100
Acceleration Tx, Ty, Tz (mm/s ²)	± 7 000
Acceleration Rx, Ry, (°/s2)	1 200
Acceleration Rz (°/s²)	600
Mechanical properties	
Payload capacity (kg) (vertical orientation only)	6 000
Motor type	Brushless
Miscellaneous	
Operating temperature range (°C)	0 to + 50
Size mobile platform (mm)	Ø 2 100
Height in middle position (mm)	~ 3 311
Mass (kg)	~ 3 000
Cable length (m)	15
Options	IP 64 motor protection ATEX compatibility Acquisition and stora API Customized platform
Controller	
Interface	Ethernet
Power supply	380 VAC (three-phase

380 VAC (three-phase) / 250 A

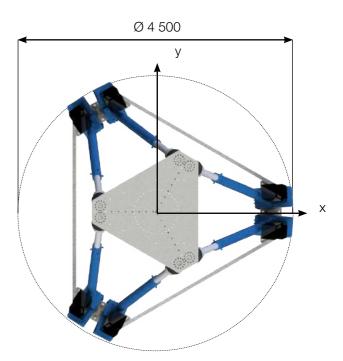
The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.



Hexapod in middle position



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