## **BORA** hexapod

## High resolution hexapod small size



## **KEY FEATURES**

- Payload capacity up to 10 kg
- Linear travel range ± 20 mm
- Angular travel range ± 15 °
- Height in middle position 145 mm

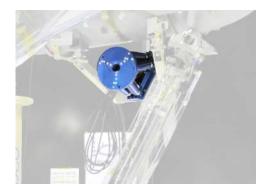


## **APPLICATIONS**

- Instrumentation
- Optics
- Aeronautics and spatial
- Metrology
- Testing laboratories
- Semiconductors
- Synchrotrons



This hexapod places a sample at the centre of two large rotation stages. With this installation, hexapod mounting orientation varies between 0° and 90°. Advantages of the hexapod are: high stability, stiffness and repeatability of the sample position with respect to the rotation stages independently of their orientations.



Alignment of a mirror with high precision on a space telescope. When the hexapod has correctly positioned the mirror, the user fixes the mirror and takes the hexapod off the structure.



Two BORA hexapods position Kirkpatrick-Baez (KB) mirrors with high stability and resolution to improve the beam quality on a synchrotron beamline.



Some HV BORA hexapods are positioning the high reflectivity mirrors of a Fabry-Perot cavity in order to optimize their alignment and thereby the cavity finesse.



|   | BORA   |  |
|---|--|--|
| Motion and positioning  |  |  |
| Travel range Tx, Ty (mm)  | ± 20   |  |
| Travel range Tz (mm)  | ± 10   |  |
| Travel range Rx, Ry (deg)   | ± 10   |  |
| Travel range Rz (deg)   | ± 15   |  |
| Resolution Tx, Ty, Tz (µm)  | 0.1  |  |
| Resolution Rx, Ry, Rz (µrad)  | 2  |  |
| Repeatability Tx, Ty, Tz (µm)   | ± 0.4  |  |
| Repeatability Rx, Ry, Rz (µrad)                                       | ± 3.2  |  |
| Speed Tx, Ty (mm/s)   | 2  |  |
| Speed Tz (mm/s)   | 1  |  |
| Speed Rx, Ry (deg/s)  | 1  |  |
| Speed Rz (deg/s)  | 2  |  |
| Mechanical properties   |  |  |
| Stiffness X, Y (N/µm)   | 1  |  |
| Stiffness Z (N/µm)  | 10   |  |
| Payload capacity (kg) (vertical orientation / horizontal orientation) | 10/5   |  |
| Motor type  | DC motor, gearhead   |  |
| Miscellaneous   |  |  |
| Operating temperature range (°C)                                      | 0 to + 50  |  |
| Materials   | Aluminum, steel, stainless steel   |  |
| Size mobile platform (mm)   | Ø 160  |  |
| Central aperture (mm)   | $\varnothing$ 43 for mobile platform ; $\varnothing$ 36 for fixed platform                                       |  |
| Height in middle position (mm)  | 145  |  |
| Mass (kg)   | 4.3  |  |
| Cable length (m)  | 3  |  |
| Options   | Clean room compatibility Vacuum compatibility Low temperature compatibility down to -40°C Hand-held control unit |  |
| Controller  |  |  |
| Controller type   | NAOS or ALPHA+ if cable length > 10 m or temperature < 0°C   |  |
| Interface   | Ethernet   |  |
| Power supply  | 110-240 VAC / 50-60 Hz   |  |

The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.

