

NOTUS hexapod

Mid-sized dynamic hexapod

III Symétrie

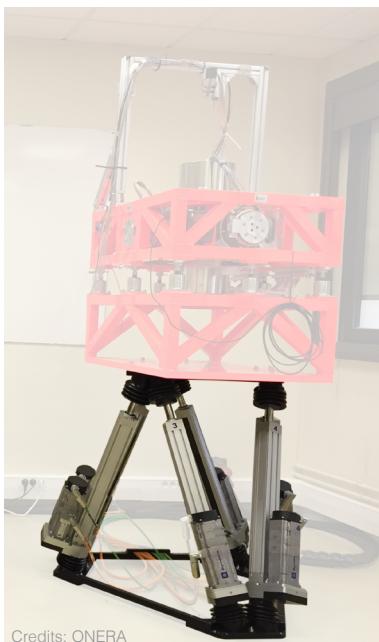


KEY FEATURES

- Payload capacity 200 kg
- Linear travel range ± 250 mm
- Angular travel range $\pm 25^\circ$
- Compact

APPLICATIONS

- Motion simulator
- Naval
- Swell simulator
- Biomedical
- Defense
- Optics



Credits: ONERA



Credits: SPHEREA Test & Services

NOTUS enables testing the gyroscopic platform of a cold atom gravimeter that will be later installed on a ship by ONERA. The hexapod reproduces the swell motions and the ship vibrations.

NOTUS hexapod allows to test the stabilization system of a camera that can be later installed on a tank, a truck or a boat.

NOTUS hexapod helps to characterize and calibrate electro-optics gimbals that will be later installed on helicopters.



	NOTUS P	NOTUS V
	for 200 kg payload	for 100 kg payload
Motion and positioning		
Travel range Tx, Ty (mm)	± 250	± 250
Travel range Tz (mm)	± 200	± 200
Travel range Rx, Ry (deg)	± 25	± 25
Travel range Rz (deg)	± 30	± 30
Speed Tx, Ty, (mm/s)	± 800	± 1 200
Speed Tz (mm/s)	± 300	± 640
Speed Rx, Ry, Rz (°/s)	± 50	± 135
Acceleration Tx, Ty (mm/s ²)	± 10 000	± 10 000
Acceleration Tz (mm/s ²)	± 6 000	± 10 000
Acceleration Rx, Ry, Rz (°/s ²)	± 1 000	± 2 000
Mechanical properties		
Payload capacity (kg) (vertical orientation only)	200	100
Motor type	Brushless	Brushless
Miscellaneous		
Operating temperature range (°C)	0 to + 40	0 to + 40
Size mobile platform (mm)	Ø 660	Ø 660
Height in middle position (mm)	~1 080	~1 080
Mass (kg)	~ 120	~ 120
Cable length (m)	7	7
Options	Outdoor Wave basin Specific joints for large angles Extra Rz rotation in the mobile platform (C axis) Acquisition (storage of motions) API External real-time trajectory control (ERTT)	
Controller		
Interface	Ethernet	
Power supply	400 VAC (three-phase) / 16 A / 50-60 Hz	

The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.

Datasheet subject to change without notice. All data are superseded by any new release. R250401



Hexapod in middle position

